M.Sc.-III/Mathematics-305ME/18

M.Sc. 3rd Semester Examination, 2018

MATHEMATICS

(Mathematical Moding of Dynamical Systems)

Paper: 305ME

Course ID : 32155

Time: 2 Hours

Full Marks: 40

The figures in the margin indicate full marks. Candidates are required to give their answers in their own words as far as practicable.

Notations and Symbols have their usual meanings.

Answer any five questions.

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8×5=40
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1+3+4=8

- 1. (a) For any $n \times n$ matrix A, prove that $\frac{d}{dt}(e^{At}) = A e^{At}$.
 - (b) Suppose $D = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$, a diagonal matrix. Then prove that $e^{Dt} = \begin{bmatrix} e^{\lambda_1 t} & 0 \\ 0 & e^{\lambda_2 t} \end{bmatrix}$. (c) For any identity matrix A = I, prove that $e^{At} = \begin{bmatrix} e^t & 0 \\ 0 & e^t \end{bmatrix} = I \cdot e^t$. 2+3+3=8

2. (a) State Poincare Bendixon Theorem.

- (b) Show that ẍ + p(x) ẋ + q(x)x = 0, where p(x) and q(x) are smooth functions and p(x) > 0, x ∈ ℝ has no periodic orbit.
- (c) Show that, $\dot{x} = y + \frac{x}{4}(1 2r^2)$ $\dot{y} = -x + \frac{1}{2}y(1 - r^2)$

where $r^2 = x^2 + y^2$ has at least one periodic solution.

3. (a) Define Critical point.

(b) Characterize the critical point(s) for the system $\frac{dJ}{dt} = \begin{bmatrix} \lambda & 0 \\ \gamma & \lambda \end{bmatrix} J$, where λ and γ are real. (c) Draw the phase diagram of the above system. 1+4+3=8

4. A predator – prey population model is given by

$$\frac{dN}{dt} = \gamma N \left(1 - \frac{N}{K} \right) - \frac{\alpha N P}{P + \alpha N} ,$$
$$\frac{dP}{dt} = \frac{e \alpha N P}{P + \alpha N} - v P,$$

where N is the prey population and P is the predator population; γ , k, α , e and v are positive constants.

- (a) Explain predator-prey model in terms of ecological systems.
- (b) Find the critical points.
- (c) Discuss the local asymptotical stability of the system. 2+2+4=8

M.Sc.-III/Mathematics-305ME/18 (2)

- **5.** (a) Define saddle node bifurcation.
 - (b) Consider the one-dimensional system of differential equation $\dot{x} = \mu x^2$, where μ is a parameter.
 - (i) Determine the Critical point(s).
 - (ii) Discuss the bifurcation around the Critical points.
 - (iii) Draw the bifurcation diagram.
- **6.** (a) Define Hyperbolic Critical point.
 - (b) For what values of α will the zero solution be stable for the autonomous system of differential equations,

$$\dot{x} = \alpha x + y$$

$$\dot{y} = -x$$
 2+6=8

1+(1+3+3)=8

7. (a) Prove that the equilibrium of the following system

$$\dot{x} = y - f(x)$$
$$\dot{y} = -g(x)$$

is stable under appropriate condition by Lyapunov's 2nd method.

(b) Consider the system of differential equations

$$\dot{x_1} = -2x_2 + x_2x_3$$

 $\dot{x_2} = x_1 - x_1x_3,$
 $\dot{x_3} = x_1x_2.$

Discuss the stability of the system by using Lyapunov method. 4+4=8

- 8. (a) Find the stability at origin for the system $\dot{x} = Ax$, where A is given by $A = \begin{bmatrix} \lambda & -2 \\ 1 & \lambda \end{bmatrix}$, λ is real.
 - (b) Write down the modified Lotka-Volterra model and find their equilibrium points. Also, discuss the stability of the system. 3+5=8